

## Exercise 1: parametric estimation of a resistance from current–voltage data

Consider a resistor described by the following current–voltage instantaneous relationship:

$$V_j = R \cdot i_j + e_j, \quad j = 1, 2, \dots, N \quad \Leftrightarrow \quad \begin{bmatrix} V_1 \\ \vdots \\ V_N \end{bmatrix} = \begin{bmatrix} i_1 \\ \vdots \\ i_N \end{bmatrix} \cdot R + \begin{bmatrix} e_1 \\ \vdots \\ e_N \end{bmatrix}$$

where  $R$  is the resistance,  $i$  is the current in the resistor,  $V$  is the voltage drop across the resistor terminals and  $e$  is a white noise with zero mean value and variance matrix  $\Sigma_{ee}$ . Two different datasets are available, each containing the following data vectors:

- $i = [i_1 \ \dots \ i_N]^T$ :  $N=20$  current measurements equispaced in the interval  $[1, 10] \text{ A}$ ;
- $V = [V_1 \ \dots \ V_N]^T$ :  $N=20$  noise-corrupted voltage measurements corresponding to the above current values.

**Problem:** For both the datasets, compute the following estimates of the resistance  $R$ :

- Sample Mean estimate  $\hat{R}_{SM}$ ;
- Least Squares estimate  $\hat{R}_{LS}$ ;
- Gauss-Markov estimate  $\hat{R}_{GM}$ ;
- Bayesian estimate  $\hat{R}_B$ .

Evaluate the quality of the obtained estimates, by comparing on a plot the measured and the “predicted” voltages and by comparing the estimate variances of  $\hat{R}_{LS}$ ,  $\hat{R}_{GM}$  and  $\hat{R}_B$ .

**Main steps:**

- (1) Load the data from the file `resistor_data_1.mat` (use `load` MATLAB command).
- (2) Plot on a figure the measured data (use `plot` MATLAB command).
- (3) Compute the Sample Mean estimate  $\hat{R}_{SM}$  (use `mean` MATLAB command). Plot in the figure generated at step (2) the estimated resistor characteristic  $\hat{V}_{SM} = \hat{R}_{SM} \cdot i$ .
- (4) Compute the Least Squares estimate  $\hat{R}_{LS}$  considering the noise variance matrix  $\Sigma_{ee} = \sigma_e^2 I_N$ , where  $\sigma_e^2 = 25 \text{ Volt}^2$  and  $I_N$  is the identity matrix (use `mldivide` or `\` or `pinv` MATLAB command). Plot in the figure generated at steps (2)–(3) the estimated resistor characteristic  $\hat{V}_{LS} = \hat{R}_{LS} \cdot i$ .
- (5) Compute the Gauss-Markov estimate  $\hat{R}_{GM}$ . Plot in the figure generated at steps (2)–(4) the estimated resistor characteristic  $\hat{V}_{GM} = \hat{R}_{GM} \cdot i$ .
- (6) Considering  $R$  as a scalar random variable uncorrelated with the noise sequence  $e$  (i.e.,  $\Sigma_{Re} = E[(R - \bar{R})e^T] = \mathbf{0}_{1 \times N}$ ), compute the Bayesian estimate  $\hat{R}_B$ :

$$\hat{R}_B = \bar{R} + \Sigma_{RV} \Sigma_{VV}^{-1} (V - \bar{V})$$

where:

- $\bar{R} = E[R] = a \text{ priori}$  mean value of  $R$ , to be assumed early (try with a value around 3);
- $\Sigma_{RR} = E[(R - \bar{R})^2] = \sigma_R^2 = a \text{ priori}$  variance of  $R$ , to be assumed early (try with the following different values of  $\sigma_R^2$ : 10, 1, 0.1, 0.01);
- $\bar{V} = E[V] = E[R \cdot i + e] = E[R \cdot i] + E[e] = E[R] \cdot i = \bar{R} \cdot i$ ;
- $\Sigma_{VV} = E[(V - \bar{V})(V - \bar{V})^T] = E[(R \cdot i + e - \bar{R} \cdot i)(R \cdot i + e - \bar{R} \cdot i)^T]$   
 $= E[((R - \bar{R}) \cdot i + e)((R - \bar{R}) \cdot i + e)^T]$   
 $= E[((R - \bar{R}) \cdot i)((R - \bar{R}) \cdot i)^T] + E[((R - \bar{R}) \cdot i)e^T] + E[e((R - \bar{R}) \cdot i)^T] + E[ee^T]$   
 $= E[(R - \bar{R})^2] \cdot i \cdot i^T + i \cdot E[(R - \bar{R})e^T] + E[e(R - \bar{R})] \cdot i^T + E[ee^T]$   
 $= \Sigma_{RR} \cdot i \cdot i^T + i \cdot \Sigma_{Re} \cdot i^T + \Sigma_{ee} = \sigma_R^2 \cdot i \cdot i^T + \Sigma_{ee}$ ;
- $\Sigma_{RV} = E[(R - \bar{R})(V - \bar{V})^T] = E[(R - \bar{R})(R \cdot i + e - \bar{R} \cdot i)^T]$   
 $= E[(R - \bar{R})(R \cdot i - \bar{R} \cdot i)^T + (R - \bar{R})e^T] = E[(R - \bar{R})(R \cdot i - \bar{R} \cdot i)^T] + E[(R - \bar{R})e^T]$   
 $= E[(R - \bar{R})(R - \bar{R}) \cdot i^T] + \Sigma_{Re} = E[(R - \bar{R})^2] \cdot i^T = \sigma_R^2 \cdot i^T$ .

Plot in the figure generated at steps (2)–(5) the estimated resistor characteristic  $\hat{V}_B = \hat{R}_B \cdot i$ .

- (7) Compute and compare the variances of the estimates  $\hat{R}_{LS}$ ,  $\hat{R}_{GM}$  and  $\hat{R}_B$ .
- (8) Repeat the steps (1)–(7) with the data stored in the file `resistor_data_2.mat`, using in steps (4)–(7) a noise variance matrix  $\Sigma_{ee}$  consistent with the data.

## Possible solution under MATLAB (file Lab3\_E1A.m)

```
%% Laboratory 3 - Estimation, filtering and system identification - Prof. M. Taragna
% *Exercise 1: Parametric estimation of a resistance from current-voltage data*
% *stored in |resistor_data_1.mat|*
%% Introduction
% The program code may be splitted in sections using the characters "%%".
% Each section can run separately with the command "Run Section"
% (in the Editor toolbar, just to the right of the "Run" button). You can do the
% same thing by highlighting the code you want to run and by using the button
% function 9 (F9). This way, you can run only the desired section of your code,
% saving your time. This script can be considered as a reference example.

clear all, close all, clc

%% Procedure
% # Load the file |resistor_data_1.mat| containing the current-voltage data
% # Plot the voltage measurements versus the current measurements
% # Estimate the resistance using the Sample Mean algorithm
% # Plot the estimated approximation versus the experimental data
% # Estimate the resistance using the Least Squares algorithm
% # Plot the estimated approximation versus the experimental data
% # Estimate the resistance using the Gauss-Markov algorithm
% # Plot the estimated approximation versus the experimental data
% # Estimate the resistance using the Bayesian method
% # Plot the estimated approximation versus the experimental data

%% Problem setup

% Step 1: load of data

load resistor_data_1.mat
% i = current measured in Ampere
% V = voltage measured in Volt

N = length(i); % N = number of data

% Step 2: plot of data

figure, plot(i,V,'ok'),
axis([min(i),max(i),0,35]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data',4)

%% Estimation of the resistance using the Sample Mean algorithm

% Step 3: computation of the parameter estimate as mean of the R values
% derived from the Ohm's law for each couple of current-voltage data

R_SM = mean(V./i)    % Form #1: using the "mean" operator

R_SM_ = V*(1./i)/N % Form #2: using the Sample Mean definition

% Step 4: graphical comparison of the results

V_SM = R_SM*i;
figure, plot(i,V,'ok', i,V_SM,'-b'),
axis([min(i),max(i),0,35]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate',4)

%% Estimation of the resistance using the Least Squares algorithm

% Step 5: computation of the parameter estimate

Phi=i;
R_LS=Phi\V    % Form #1: using the "\" operator (more reliable)
```

```

A=pinv(Phi); % more reliable than inv(Phi'*Phi)*Phi'
R_LS_=A*V % Form #2: using the pseudoinverse matrix
sigma_e = 5;
Sigma_ee = sigma_e^2*eye(N);
Sigma_R_LS = pinv(Phi)*Sigma_ee*pinv(Phi);

% Step 6: graphical comparison of the results

V_LS = R_LS*i;
figure, plot(i,V,'ok', i,V_SM,'-b', i,V_LS,'-r'),
axis([min(i),max(i),0,35]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate','Least Squares estimate',4)

%% Estimation of the resistance using the Gauss-Markov algorithm

% Step 7: computation of the parameter estimate
% Note that the Gauss-Markov estimate coincides with the Least Squares
% estimate when the same weights are used for all the measurements

R_GM = inv(Phi'*inv(Sigma_ee)*Phi)*Phi'*inv(Sigma_ee)*V
Sigma_R_GM = inv(Phi'*inv(Sigma_ee)*Phi)

% Step 8: graphical comparison of the results

V_GM = R_GM*i;
figure, plot(i,V,'ok', i,V_SM,'-b', i,V_LS,'-r', i,V_GM,'--k'),
axis([min(i),max(i),0,35]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate','Least Squares estimate',...
'Gauss-Markov estimate',4)

%% Estimation of the resistance using the Bayesian method

% Step 9: computation of the parameter estimate, assuming:
% - R_bar = a priori mean value of R = 3 (to be assumed early)
% - Sigma_RR = a priori variance of R = 10, 1, 0.1, 0.01 (to be assumed early)
% - V_bar = mean value of V = R_bar*i
% - Sigma_VV = Sigma_RR*i*i' + Sigma_ee
% - Sigma_RV = Sigma_RR*i'

R_bar = 3; % Try also with R_GM
Sigma_RR = [10, 1, 0.1, 0.01];
V_bar = R_bar*i;
for k=1:length(Sigma_RR),
    Sigma_VV = Sigma_RR(k)*i*i' + Sigma_ee;
    Sigma_RV = Sigma_RR(k)*i';
    R_B(k) = R_bar + Sigma_RV * inv(Sigma_VV) * (V-V_bar);
    Sigma_R_B(k) = Sigma_RV * inv(Sigma_VV) * Sigma_RV'; % estimate variance
    Sigma_R_minus_R_B(k) = Sigma_RR(k) - Sigma_R_B(k); % a posteriori variance
    V_B(:,k) = R_B(k)*i;
end
Sigma_RR, R_B, Sigma_R_B, Sigma_R_minus_R_B

% Step 10: graphical comparison of the results

figure, plot(i,V,'ok', i,V_SM,'-b', i,V_LS,'-r', i,V_GM,'--k', ...
i,V_B(:,1),'-m', i,V_B(:,2),'--m', ...
i,V_B(:,3),'-c', i,V_B(:,4),'--c'),
axis([min(i),max(i),0,35]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate','Least Squares estimate',...
'Gauss-Markov estimate', ...
['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(1)),')'], ...
['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(2)),')'], ...
['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(3)),')'], ...
['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(4)),')'], 4)

```

## Possible solution under MATLAB (file Lab3\_E1B.m)

```
%% Laboratory 3 - Estimation, filtering and system identification - Prof. M. Taragna
% *Exercise 1: Parametric estimation of a resistance from current-voltage data*
% *stored in |resistor_data_2.mat|*
%% Introduction
% The program code may be splitted in sections using the characters "%%".
% Each section can run separately with the command "Run Section"
% (in the Editor toolbar, just to the right of the "Run" button). You can do the
% same thing by highlighting the code you want to run and by using the button
% function 9 (F9). This way, you can run only the desired section of your code,
% saving your time. This script can be considered as a reference example.

clear all, close all, clc

%% Procedure
% # Load the file |resistor_data_2.mat| containing the current-voltage data
% # Plot the voltage measurements versus the current measurements
% # Estimate the resistance using the Sample Mean algorithm
% # Plot the estimated approximation versus the experimental data
% # Define the noise variance matrix consistent with experimental data
% # Estimate the resistance using the Least Squares algorithm
% # Plot the estimated approximation versus the experimental data
% # Estimate the resistance using the Gauss-Markov algorithm
% # Plot the estimated approximation versus the experimental data
% # Estimate the resistance using the Bayesian method
% # Plot the estimated approximation versus the experimental data

%% Problem setup

% Step 1: load of data

load resistor_data_2.mat
% i = current measured in Ampere
% V = voltage measured in Volt

N = length(i); % N = number of data

% Step 2: plot of data

figure, plot(i,V,'ok'),
axis([min(i),max(i),0,45]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data',4)

%% Estimation of the resistance using the Sample Mean algorithm

% Step 3: computation of the parameter estimate as mean of the R values
% derived from the Ohm's law for each couple of current-voltage data

R_SM = mean(V./i)    % Form #1: using the "mean" operator
R_SM_ = V*(1./i)/N % Form #2: using the Sample Mean definition

% Step 4: graphical comparison of the results

V_SM = R_SM*i;
figure, plot(i,V,'ok', i,V_SM,'-b'),
axis([min(i),max(i),0,45]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate',4)

%% Estimation of the resistance using the Least Squares algorithm

% Step 5: definition of the noise variance matrix consistent with data

sigma_e = 5;
Sigma_ee = sigma_e^2*eye(N); % Like with resistor_data_1.mat datafile
```

```

% From data plot, the 7-th sample is not consistent with the others,
% being highly corrupted. As a consequence, the weight of this sample
% should be reduced. This can be obtained by forcing a high value of
% the corresponding variance in the noise variance matrix, since each
% variance represents the measure uncertainty: a larger variance reduces
% the measure reliability. For example, instead of sigma_e^2 = 5^2,
% the value (5*sigma_e)^2 = 25^2 can be forced.
Sigma_ee(7,7) = (5*sigma_e)^2;

% Step 6: computation of the parameter estimate

Phi=i;
R_LS=Phi\V % Form #1: using the "\" operator (more reliable)

A=pinv(Phi); % more reliable than inv(Phi'*Phi)*Phi'
R_LS_=A\V % Form #2: using the pseudoinverse matrix

Sigma_R_LS = pinv(Phi)*Sigma_ee*pinv(Phi)'

% Step 7: graphical comparison of the results

V_LS = R_LS*i;
figure, plot(i,V,'ok', i,V_SM,'-b', i,V_LS,'-r'),
axis([min(i),max(i),0,45]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate','Least Squares estimate',4)

%% Estimation of the resistance using the Gauss-Markov algorithm

% Step 8: computation of the parameter estimate
% Note that the Gauss-Markov estimate differs from the Least Squares
% estimate when different weights are used for the measurements

R_GM = inv(Phi'*inv(Sigma_ee)*Phi)*Phi'*inv(Sigma_ee)*V
Sigma_R_GM = inv(Phi'*inv(Sigma_ee)*Phi)

% Step 9: graphical comparison of the results

V_GM = R_GM*i;
figure, plot(i,V,'ok', i,V_SM,'-b', i,V_LS,'-r', i,V_GM,'--k'),
axis([min(i),max(i),0,45]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate','Least Squares estimate',...
'Gauss-Markov estimate',4)

%% Estimation of the resistance using the Bayesian method

% Step 10: computation of the parameter estimate, assuming:
% - R_bar = a priori mean value of R = 3 (to be assumed early)
% - Sigma_RR = a priori variance of R = 10, 1, 0.1, 0.01 (to be assumed early)
% - V_bar = mean value of V = R_bar*i
% - Sigma_VV = Sigma_RR*i*i' + Sigma_ee
% - Sigma_RV = Sigma_RR*i'

R_bar = 3; % Try also with R_GM
Sigma_RR = [10, 1, 0.1, 0.01];
V_bar = R_bar*i;
for k=1:length(Sigma_RR),
    Sigma_VV = Sigma_RR(k)*i*i' + Sigma_ee;
    Sigma_RV = Sigma_RR(k)*i';
    R_B(k) = R_bar + Sigma_RV * inv(Sigma_VV) * (V-V_bar);
    Sigma_R_B(k) = Sigma_RV * inv(Sigma_VV) * Sigma_RV'; % estimate variance
    Sigma_R_minus_R_B(k) = Sigma_RR(k) - Sigma_R_B(k); % a posteriori variance
    V_B(:,k) = R_B(k)*i;
end
Sigma_RR, R_B, Sigma_R_B, Sigma_R_minus_R_B

```

```
% Step 11: graphical comparison of the results

figure, plot(i,V,'ok', i,V_SM,'-b', i,V_LS,'-r', i,V_GM,'--k', ...
    i,V_B(:,1),'-m', i,V_B(:,2),'--m', ...
    i,V_B(:,3),'-c', i,V_B(:,4),'--c'),
axis([min(i),max(i),0,45]), grid, title('Measured data and approximations'),
xlabel('Current{\it i} in A'), ylabel('Voltage{\it V} in V'),
legend('Measured data','Sample Mean estimate','Least Squares estimate',...
    'Gauss-Markov estimate', ...
    ['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(1)),')'], ...
    ['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(2)),')'], ...
    ['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(3)),')'], ...
    ['Bayesian estimate (\sigma_R^2=', num2str(Sigma_RR(4)),')'],4)
```